Course Name:Control Systems EngineeringCourse No.:EE 301Credits:2.5-0.5-0-3PrerequisitesB.Tech.Students intended for:B.Tech.Elective or CompulsoryOdd/EvenCourse contents:Image: Content State State

Basic concepts: Introduction, basic terminology, objective of subject, some basic examples, Notion of feedback; open- and closed-loop systems.

Mathematical Models: Representation of physical systems and analogous systems, Lapalce transforms, block diagrams, transfer functions for different type of systems, block diagrams reduction techniques; Signal flow graphs and Mason's gain formula.

Control hardware and their models: Potentiometers, synchros, LVDT, DC and AC servo motors, tachogenerators, electro-hydraulic valves, and pneumatic actuators.

Time-domain analysis: Time domain performance criterion, transient response of first order, second order and higher order systems; Steady state errors: Static and dynamic error constants, system types, steady state errors for unity and non unity feedback systems, performance analysis for P, PI and PID controllers.

Frequency-domain analysis: Bode and polar plots, frequency-domain specifications, correlation between transient response and frequency response.

Stability analysis: Concept of stability by Routh stability criterion, Nyquist stability criterion, gain and phase margins, relative stability, constant M and N circles, Nichol's chart and its application.

Root-locus technique: Nature of root-locus, rules of construction, root-locus analysis of control systems.

Compensation: Types of compensation, Proportional, PI and PID controllers; Lead-lag compensators.

State-space concepts: Eigen values and eigen vectors; Solution of state equations; Controllability; Observability; pole placement result, Minimal representations(**if time permits**).

Non-Linear systems: Characteristics of non-linear systems, types of non-linearities, phase-plane analysis, limit cycles and describing functions (**if time permits**).

References:

- 1. Nagrath I. J. and Gopal M., Control System Engineering.
- 2. Kuo B. C., Automatic Control Systems.
- 3. Ogata K., Modern Control Engineering.
- 4. Gopal M., Control Systems: Principle and Design.
- 5. NPTEL Video Lectures on Control Engg. by Prof. S. D Agashe.
- 6. NPTEL Lecture Notes on Control Systems by Prof. M. Gopal.
- 7. Dorf R. C. and Bishop R. H., Modern Control Systems.
- 8. Norman S. N., Control Systems Engineering.
- 9. IEEE Transactions on Automatic Control.
- 10. IEEE Transactions on Control Systems Technology.